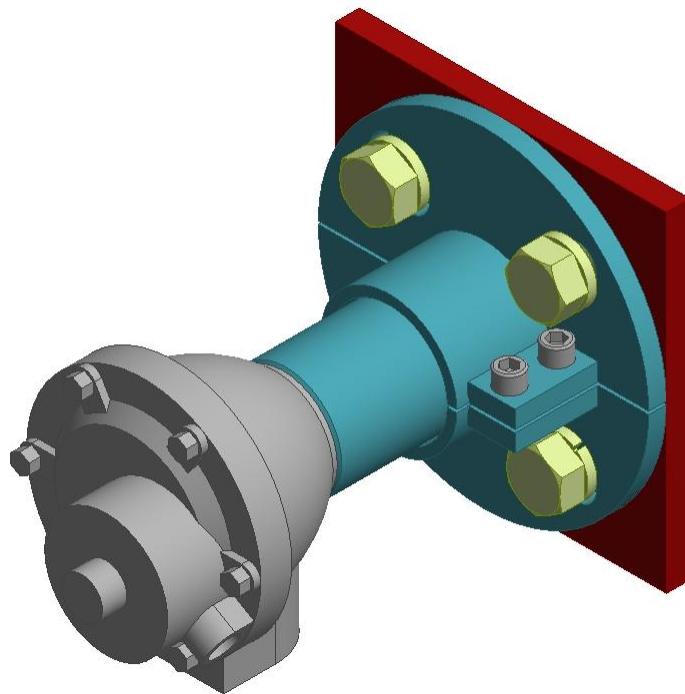




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CLEAN SWEEP AIR CONTROL



Installation & Maintenance Manual

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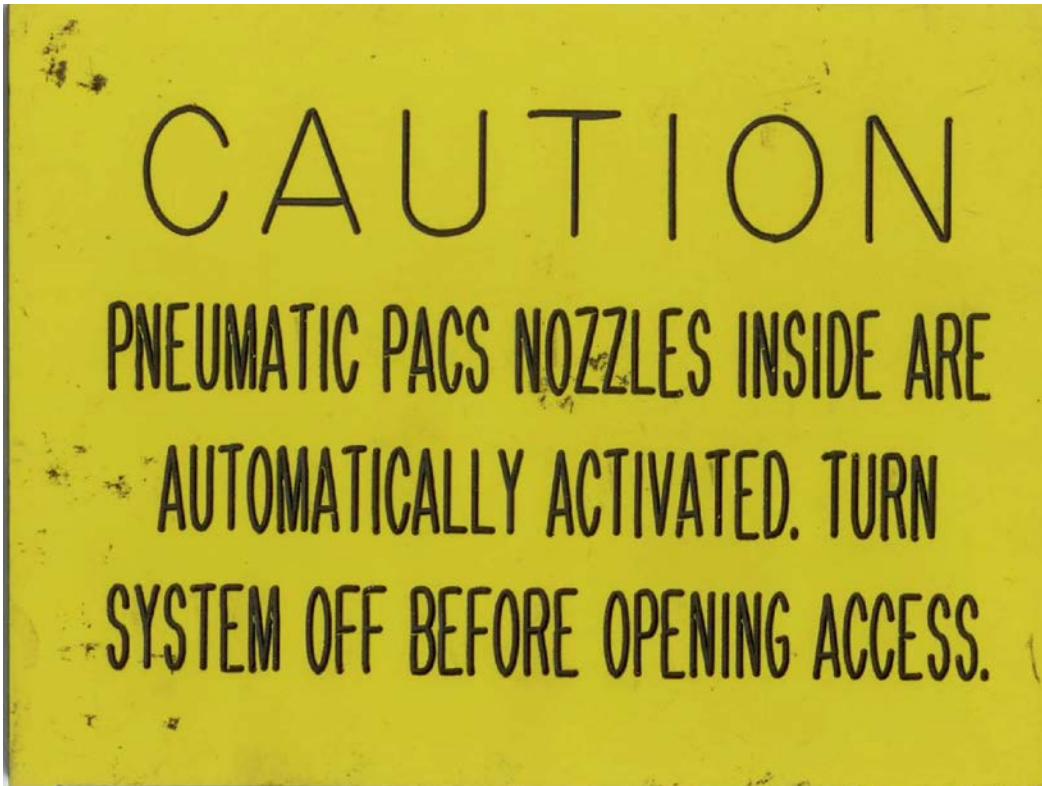
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1.0

SYSTEM PRECAUTION:

Clean Sweep Air Control system operate at 80 - 100 PSI pressure. Place appropriate safety signage on all access doors where Clean Sweep Nozzles are installed. DO NOT inspect Clean Sweep nozzles when operating. Always shut off and tag out Clean Sweep Air Control systems prior to entering or inspecting chutes or bins where Clean Sweep nozzles are installed.

CAUTION: Never visually inspect chutes when Clean Sweep Nozzles are firing. Always turn off and tag out Clean Sweep Air Control System prior to chute inspection or entry



2.0 THEORY OF OPERATION

The Clean Sweep Air Control System works on the principle that compressed air can be utilized to remove buildups of wet, sticky material from the walls of bulk solids handling system chutes, bins and hoppers. Compressed air (80 to 100 psig) has been proven to exert enough energy to remove large accumulations of build up on chute walls. The Clean Sweep System does this without interfering with normal material handling process and operations. Loss of material flow due to pluggage is virtually eliminated in areas where Clean Sweep nozzles are correctly positioned.

A standard Clean Sweep Air Control System consists of properly positioned Clean Sweep nozzles, compressed air reservoir tank, and necessary electronic controls. A blast of compressed air is delivered sequentially to each nozzle through a quick-opening/quick-closing air operated diaphragm valve. Each nozzle directs compressed air in a 360° pattern along the surface of the chutework for a radial distance of approximately two feet. The air dislodges and breaks up the layer of material buildup, which is then carried away by gravity or other material flowing through the chute.

All Clean Sweep valve bodies are mounted flush to a chute/bin surface with only the hardened steel valve nozzle head extending into the material stream. When activated by a 1/10 second blast of compressed air, the valve nozzle head extends into the material stream approximately 1/8 of an inch. Up to a 3' radius is cleaned and the valve nozzle head retracts back to its original position through spring loading. The system will continue to cycle through all nozzles until the buildup is removed (adjustable depending on material conditions).

A complete Clean Sweep Air Control System includes the following: (Reference Figure A1)

- **Nozzle Assembly** - Includes limited travel hardened steel nozzles with high pressure hose, solenoid valves, flanged clamp bracket, mounting (weld) plate with mounting bolts, high pressure hose fittings & control tubing.
- **Tank Air Supply Assembly** - Includes 30 – 60 gallon ASME certified accumulator tank with pressure gauge, auto tank drain, pressure switch and moisture trap.
- **Control System Assembly** - Includes control card(s), panel switches and indicator lights for automatic and manual operation.

3.0 INSTALLATION

If your Clean Sweep System will NOT be installed by Benetech personnel, or you have chosen to expand the Clean Sweep System yourself, installing/expanding your Clean Sweep System can be completed per the following instructions:

A. Clean Sweep Air Control System Installation

1. Determining where to locate Clean Sweep nozzles:
Clean Sweep nozzles should be located at the area where material first starts to build up. From this initial point, additional Clean Sweep nozzles should be installed in an upward direction throughout the pluggage areas. Typical areas are; dog legs, impact zones, bin to hopper transition, hopper corners, slide areas, hopper ledges, corner transitions, impact points, chute discharge etc. Nozzles are typically located approximately 3' apart. It is recommended that the personnel responsible for clearing and cleaning pluggage be consulted to confirm where build up first starts.
2. After nozzle locations have been selected (technical assistance provided by your Benetech sales or service representative is recommend), a 3" diameter hole is cut through the chute or hopper wall and lining. If the chute or hopper wall contains two (2) or more linings and there is a gap between liners, it is recommended that the gaps be filled in. PAC nozzles have been installed successfully in a variety of chute and hopper wall materials including ceramics, stainless steel and chromium carbide.
3. The square "mounting plate" (Item 1 on pg. 20) is welded to the outside of the chute or hopper wall. The 3" diameter hole in the "mounting plate" and the hole in the chute or hopper wall **MUST** line up.
4. Bolt the flanged "clamp bracket" (Item 2 on pg. 20) to the mounting plate, use only two (2) bolts (finger tight) at this time.
5. Tighten the set screw located in the "clamp bracket" this will spread the clamp apart to accept the valve body (Item 8 on pg. 20).
6. Insert the "valve body" assembly (Item 3 on pg. 20) into the "clamp bracket" until the outer edge of the valve body is flush with the internal wall surface. Loosen the set screw. Tighten both 3/8" hex head bolts (approximately 50 ft./lb.) to hold the valve body assembly in place. **NOTE: Limited travel hardened steel nozzles are pre-set, DO NOT adjust valve stem nut.**
7. Tighten the set screw.

8. Install the two (2) remaining bolts into the “mounting plate” and tighten all bolts.
9. Install a 1-1/2” all-thread nipple and air operated diaphragm valve. (See pg. 19) to the back of valve body.

NOTE: Use Teflon thread sealant on all pipe fittings.

10. Install 1/8” MNPT x 1/4” tube 90° elbow fitting into air operated diaphragm valve. (See pg. 19)
11. Locate the pilot valve solenoid box in an area so that the length of 1/4” poly tubing from the valve box to the solenoids does not exceed five feet. All tubing from the pilot box to solenoids should be (approximately) the same length. More than one pilot valve solenoid box may be required. (See pg. 19)
12. Connect 1/4” poly tubing from 1/4” tube fitting in air operated diaphragm valve to the pilot valve solenoid box with 1/4” tube x 1/8” MNPT straight fitting. Length of poly tube should not exceed five feet. (See pg. 19)
13. Locate the air accumulator tank in a suitable area (not more than 100’ from tank to PACS) that minimizes material and manpower. Run supply air to the tank and 2” pipe from the tank to the PAC area(s). NOTE: if a suitable sized accumulator tank is **not** being used, (e.g.: small air compressor) insure that a pressure switch is placed in the PACS air supply line set at 60 PSI. Pressure below this set point will deactivate PACS system. (See pg. 18 & 19)
14. Connect 1-1/2” high pressure fitting and hose from air operated diaphragm valve to 1-1/2” ball valve. Connect 1-1/2” nipple, 2” x 1-1/2” reducer bushing, and 2” coupling. (See pg. 19) Shut off valves **MUST** be installed between the air header (by others) and PAC nozzles.
15. Mount control panel, connect 120 volt, 60 Hertz, 15 amp, single phase (See pg. 18 & 21). Install conduit and wire from the control panel to the pilot valve solenoid box(s)
16. Place Caution and Warning signs on all access doors where PACS are installed.

4.0 OPERATIONS

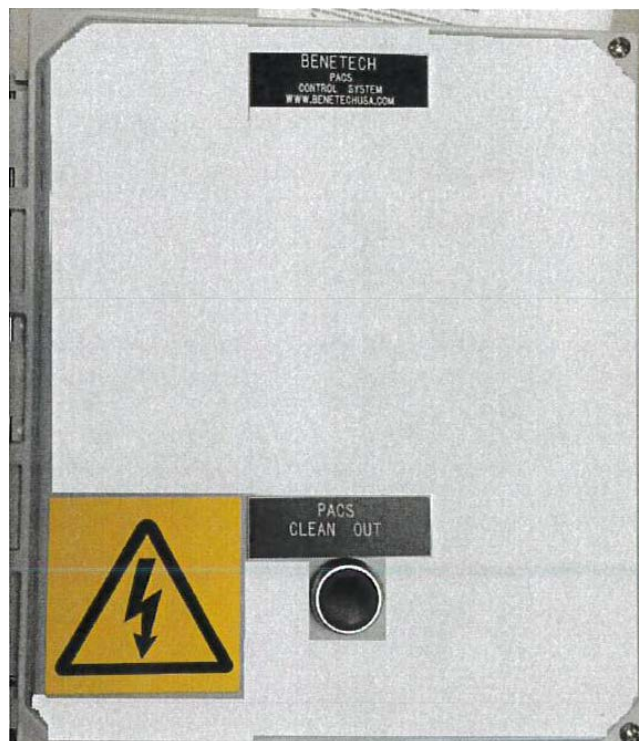
A. OVERVIEW

The system is designed to maintain material flow through hoppers, bins, or chutes using a sequential timing device to alternately fire each Clean Sweep nozzle.

The system can be interlocked with a “run permissive” to ensure that the system is only operating during times when material is present. If the “run permissive” will not be used add a jumper wire between terminal blocks 3 & 3A (See Electrical Diagram attached)

A “Clean Out” pushbutton switch (See Figure A1) activates all nozzles for one or more (programmable) cleaning cycles regardless of whether the run permissive is made or not.

FIGURE A1



B. ADJUSTMENTS

The digital timer boards located inside the control panel activate the Clean Sweep nozzles in a preset sequence and interval to insure even clearing of material. The firing order is usually from the discharge (lowest unit) of the chute or hopper to the top

C. TIMER ADJUSTMENTS

The first four (4) adjustments are made on the timer board. Follow the instructions in the attached Timer Board manual.

5.0 MAINTENANCE

A. TROUBLESHOOTING GUIDE

<u>SYMPTOM</u>	<u>CAUSE</u>	<u>REMEDY</u>
System does not operate in any mode	No power to controls Low air pressure Timer Board Faulty	Check incoming power Increase air pressure Replace timer board
System only operates in clean-out mode	Auto run permissive not made	Verify that equipment is running Check permissive contact
Nozzles will not fire in TIMED mode only	Cycle is in 'Pause' time Timer Relay fault	Wait for 'Pause' time to end Replace timer relay
Nozzle(s) will not stop blowing	Solenoid pilot stuck open Solenoid diaphragm broke or material lodged in it Tubing from pilot to solenoid leaking Output bad on timer board	Repair or replace pilot valve Repair or replace solenoid diaphragm Repair ¼" poly tubing Move to spare output or replace timer board
Nozzle(s) do not clear material build-up	Valve body not adjusted to proper depth Valve head worn or missing Solenoid valve or pilot valve not working No 120 Volt signal from timer board ¼ pilot tube too long	Refer to installation guide Repair or replace Repair or replace Move to spare output timer board or replace board Relocate pilot box to shorten tube

NOTE: For maintenance purposes, isolation valves must be installed on the individual Clean Sweep nozzles. This will allow for one or more nozzles to be removed for repair without taking the entire system out of service.

CAUTION: *Never visually inspect chutes when Clean Sweep nozzles are firing. Always turn off and tag out Clean Sweep Air Control System prior to chute inspection or entry.*

B. CLEAN SWEEP NOZZLE REPLACEMENT

NOTE: Before performing maintenance and/or adjustment, electrical power and compressed air supply must be turned off and supply header must be drained of pressure. Follow appropriate lock and tag procedures

Remove Clean Sweep valve body in reverse order of installation.

Install new Clean Sweep valve body per installation instructions.

Adjust the body to achieve the proper adjustment of the valve to the chute or wall surface by measuring the distance from the internal wall surface to the outer portion of the clamp flange that holds the main body. Insert the main body into the clamp flange the measured amount. If this is done correctly, the valve head should extend 0.125 inches past the internal chute or hopper wall.

6.0 INSTALLATION PHOTOS



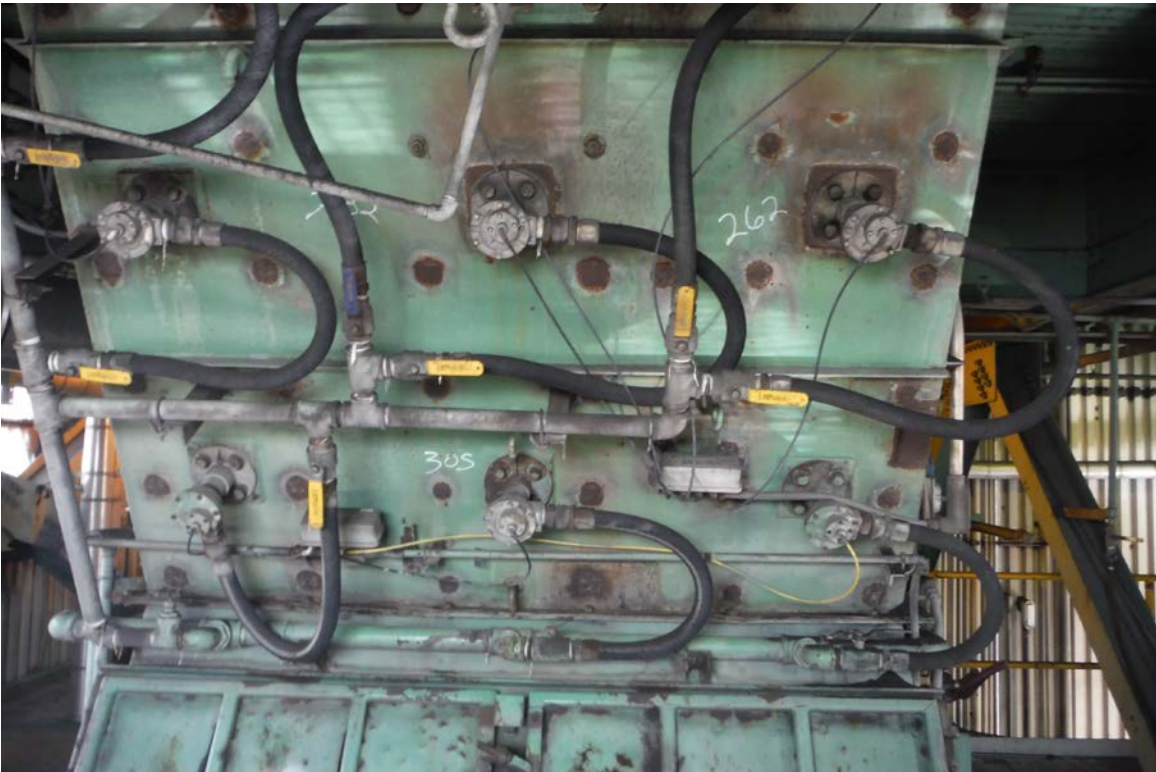
Note air supply piping installation with block valves



Clean Sweep Nozzles Installed in Chute to Remove/prevent Pluggage

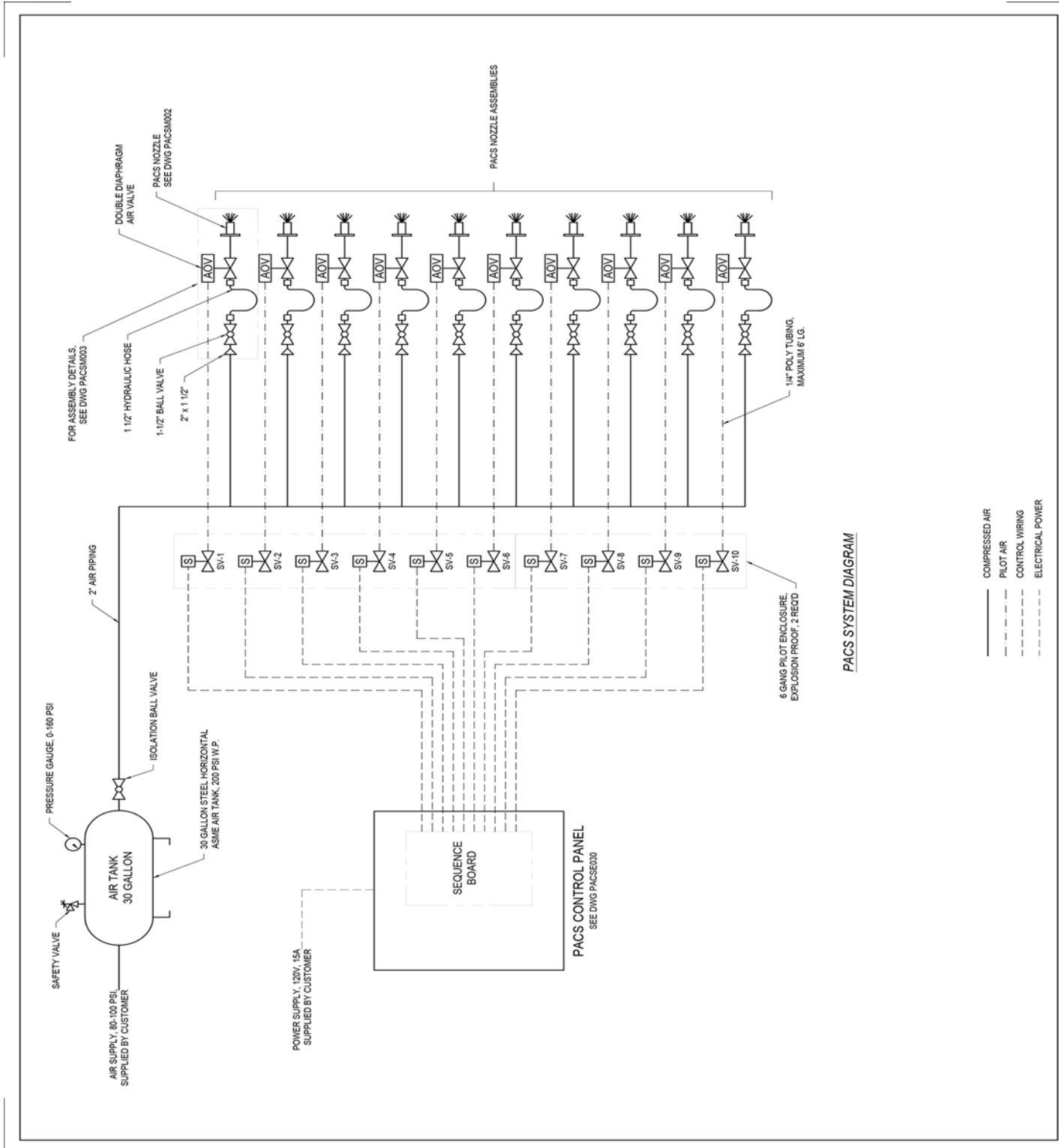


Pilot Valve Box Location and 1/4" Tube



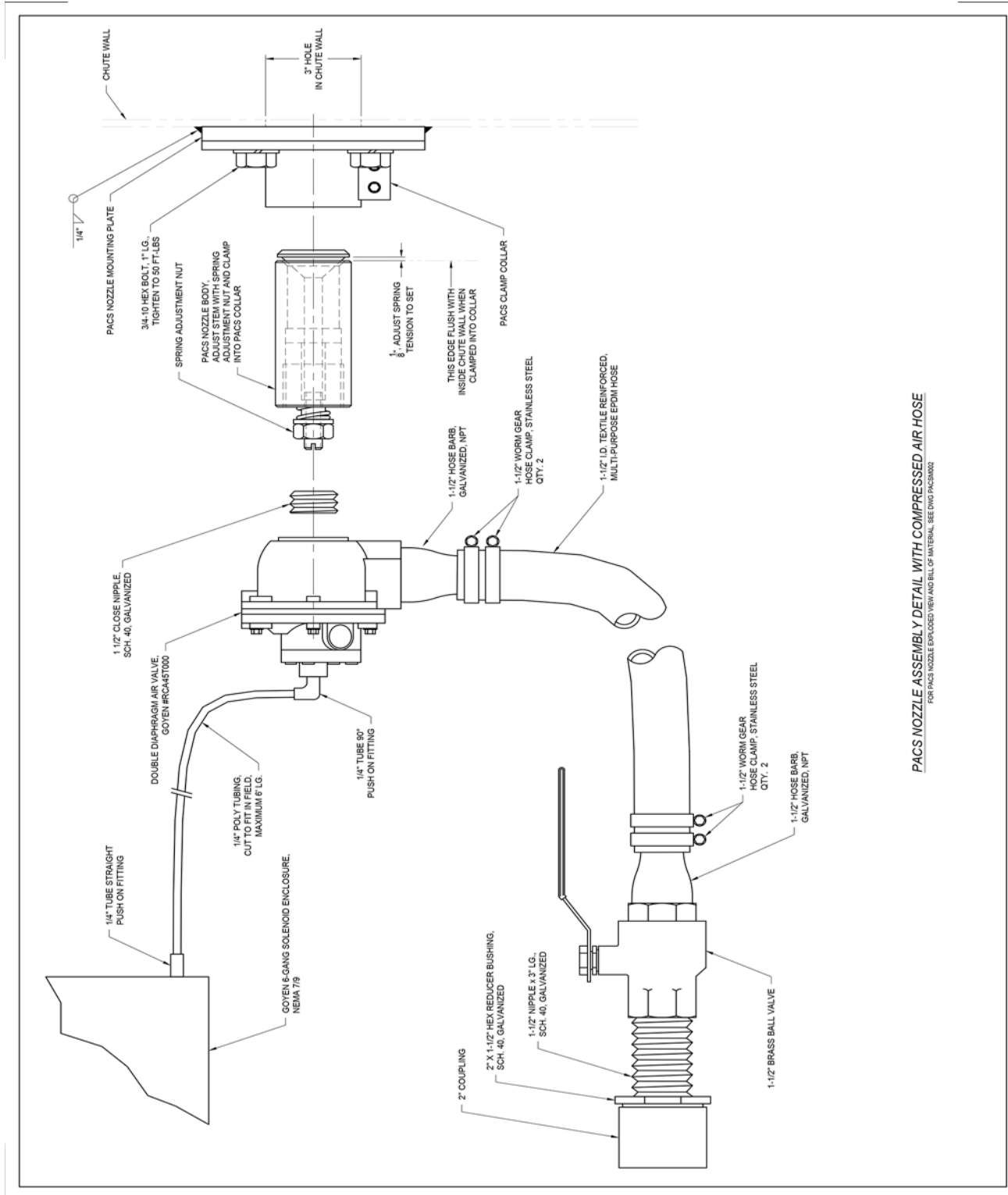


Clean Sweep nozzles Installed in Hopper Discharge: Note location of pilot box



PACS SYSTEM DIAGRAM

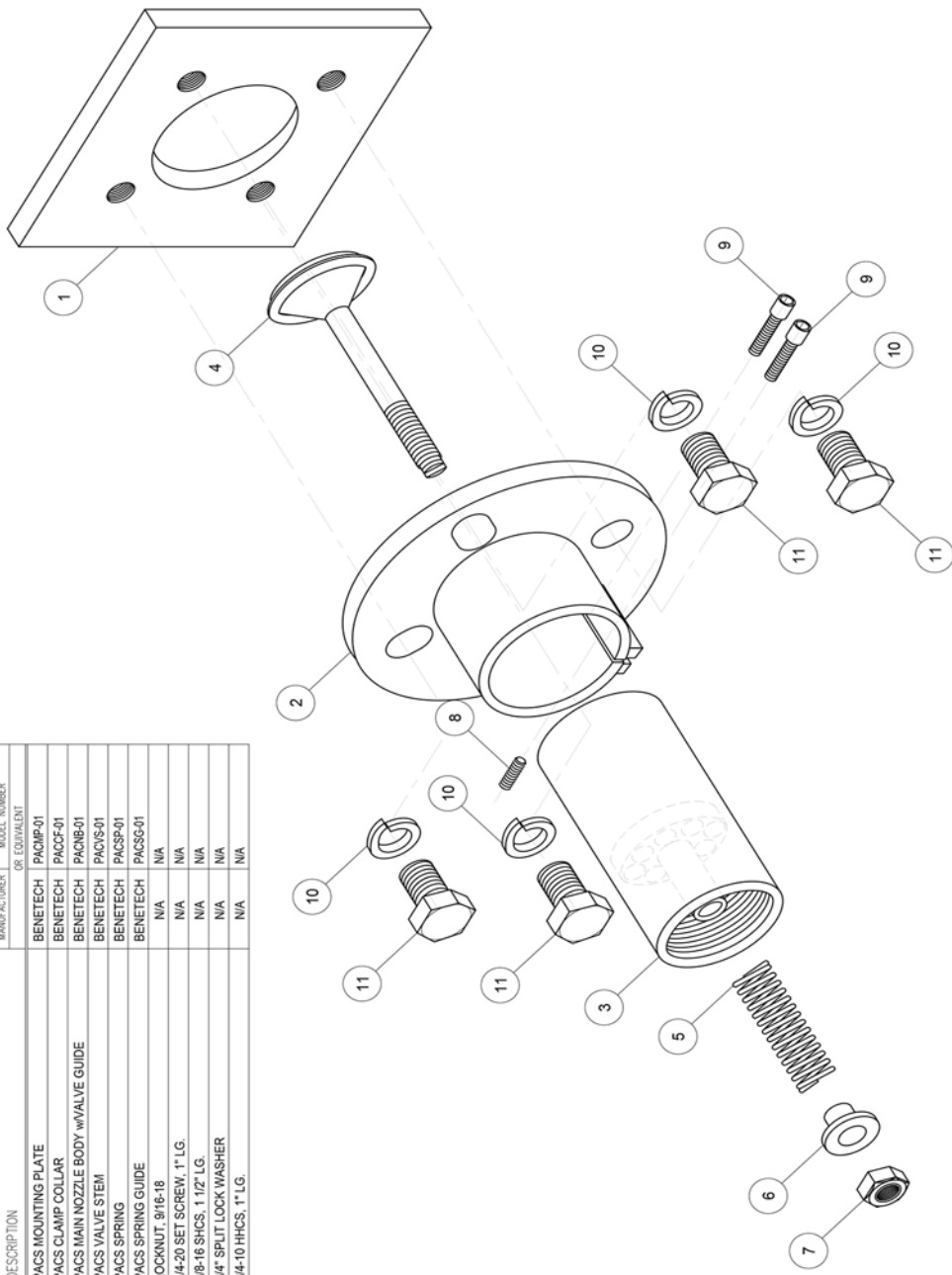
- COMPRESSED AIR
- - - PILOT AIR
- CONTROL WIRING
- · - · ELECTRICAL POWER



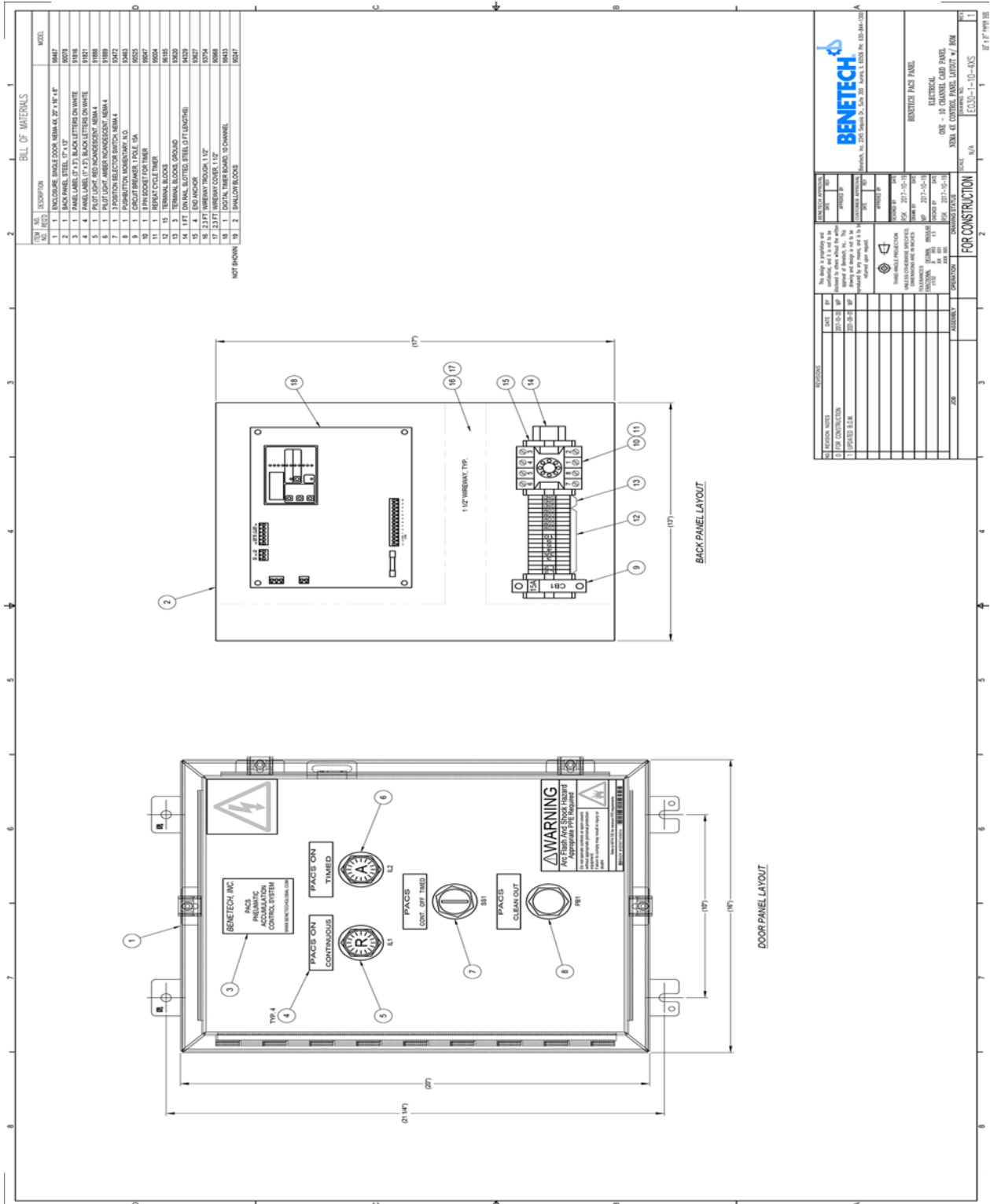
PACS NOZZLE ASSEMBLY DETAIL WITH COMPRESSED AIR HOSE
 FOR PACS NOZZLE EMPLOYED VIEW AND BILL OF MATERIAL, SEE DWG PAC3000Z

BILL OF MATERIAL

ITEM NO.	NO. REQ'D	DESCRIPTION	MANUFACTURER	MODEL NUMBER OR EQUIVALENT
1	1	PACS MOUNTING PLATE	BENETECH	PACMP-01
2	1	PACS CLAMP COLLAR	BENETECH	PACCF-01
3	1	PACS MAIN NOZZLE BODY w/VALVE GUIDE	BENETECH	PACNB-01
4	1	PACS VALVE STEM	BENETECH	PACVS-01
5	1	PACS SPRING	BENETECH	PACSP-01
6	1	PACS SPRING GUIDE	BENETECH	PACSG-01
7	1	LOCKNUT, 9/16-18	N/A	N/A
8	1	1/4-20 SET SCREW, 1" LG.	N/A	N/A
9	2	3/8-16 SHCS, 1 1/2" LG.	N/A	N/A
10	4	3/4" SPLIT LOCK WASHER	N/A	N/A
11	4	3/4-10 HHCS, 1" LG.	N/A	N/A



PACS NOZZLE EXPLODED VIEW



BILL OF MATERIALS

ITEM NO.	DESCRIPTION	QTY	MODEL
1	ENCLOSURE, SINGLE DOOR, 20" X 14" X 4"	1	84627
2	BACK PANEL, STEEL, 17" X 17"	1	86078
3	PANEL LABEL (7) BLACK LETTERS ON WHITE	7	19196
4	PANEL LABEL (7) BLACK LETTERS ON WHITE	7	19196
5	PILOT LIGHT, RED, NON-REVERSIBLE, 1/2" DIA.	1	19180
6	PILOT LIGHT, GREEN, NON-REVERSIBLE, 1/2" DIA.	1	19180
7	POSITION SELECTOR SWITCH, 1/2" DIA.	1	19472
8	PARABRAZILLON MOUNTING, 1/2" DIA.	1	19483
9	CIRCUIT BREAKER, 1 POLE, 15A	1	86525
10	TERMINAL BLOCK, 15 POS.	1	86527
11	TERMINAL BLOCK, 15 POS.	1	86527
12	TERMINAL BLOCK, 15 POS.	1	86527
13	TERMINAL BLOCK, 15 POS.	1	86527
14	1 1/2" DIN RAIL, SLOTTED, STEEL, 1 FT. LONG	1	84509
15	1 1/2" DIN RAIL, SLOTTED, STEEL, 1 FT. LONG	1	84509
16	1 1/2" DIN RAIL, SLOTTED, STEEL, 1 FT. LONG	1	84509
17	1 1/2" DIN RAIL, SLOTTED, STEEL, 1 FT. LONG	1	84509
18	DIGITAL TIMER BAND, 1/2" CHANNEL	1	84633
19	DIGITAL TIMER BAND, 1/2" CHANNEL	1	84633

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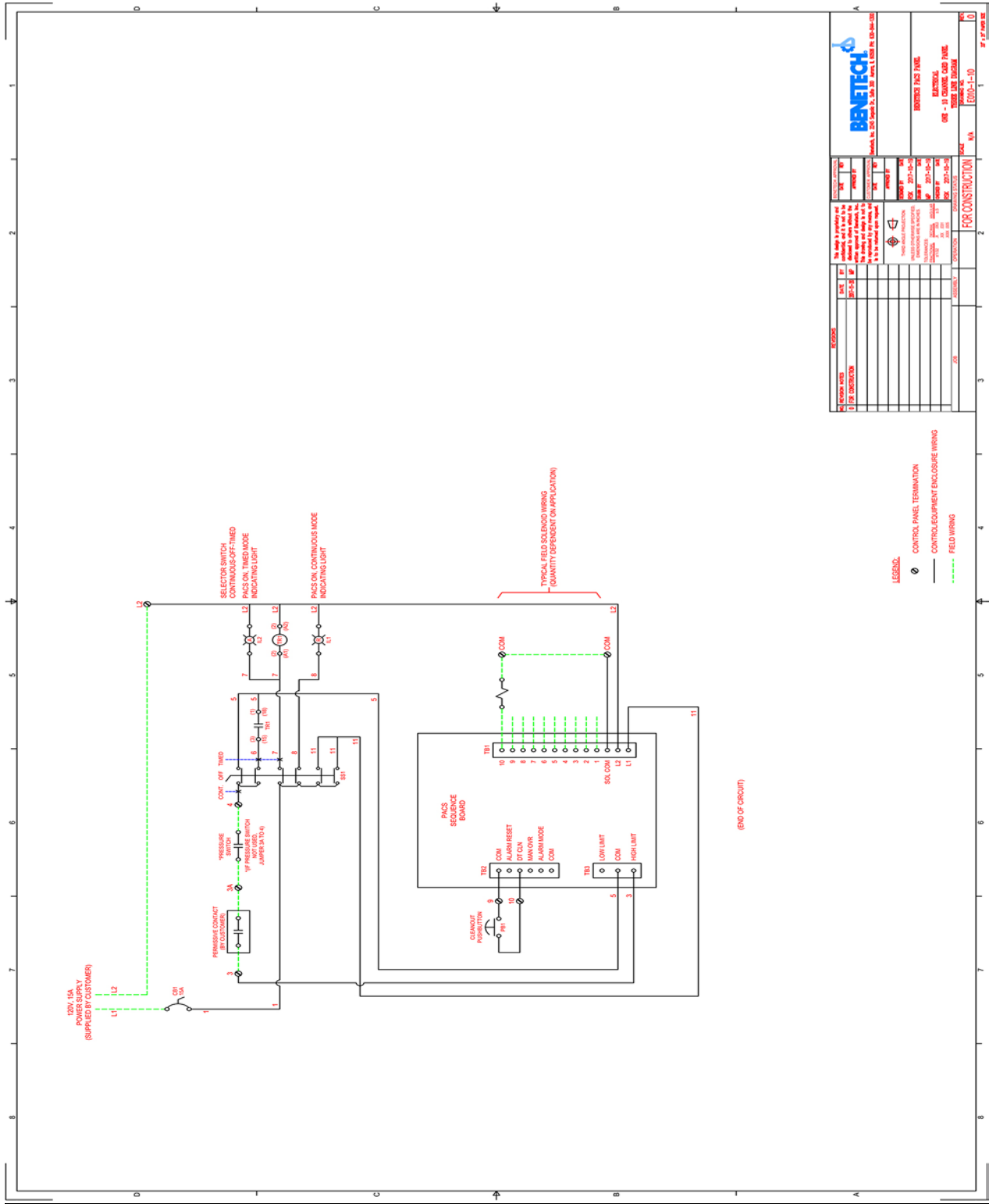
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LEGEND:

- CONTROL PANEL TERMINATION
- CONTROL EQUIPMENT ENCLOSURE WIRING
- ⋯ FIELD WIRING

REVISIONS:

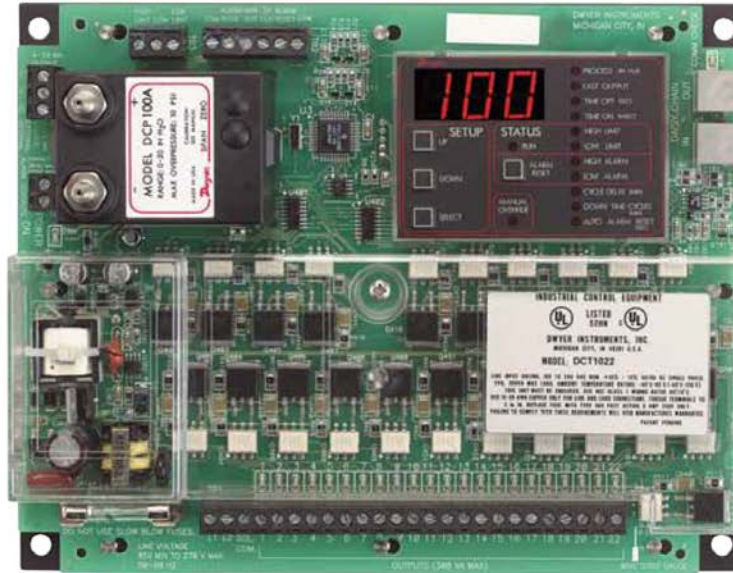
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Specifications – Installation and Operating Instructions



Thank you for purchasing the DCT1000 Dust Collector Timer Controller. You have selected a state of the art dust collector timer control that will provide years of dependable operation and service.

The DCT1000 Dust Collector Timer Controller was designed to be used with pulse-jet type dust collectors for on-demand or continuous cleaning applications.

Continuous cleaning applications do not require external inputs and can be used for time based "on-demand" cleaning through use of the cycle delay feature.

For on-demand applications, the plug-in pressure modules (DCP100A/200A) can be used to take full advantage of all the features the DCT1000 offers, or an external pressure switch (such as the Dwyer Photohelic™) can be used for High/Low limit control.

As with traditional Dwyer products, the Dwyer DCT1000 was designed so that it is easy to use, thus allowing for a quick and easy start up for your dust control applications. The contents inside this installation and operating manual will guide you through the features of the DCT1000 and how they can be applied to get the most out of your dust control requirements.

SPECIFICATIONS

DCT1000 Timer Controller:

Output Channels: 6, 10, & 22 channels. Expandable to 255 channels using DCT1122 & DCT1110 channel expander boards.

Power Requirements: 85 to 270 VAC, 50 or 60 Hz.

Solenoid Supply: 3A maximum per channel.

Fuse: 3A @ 250 VAC. Low voltage control circuitry is isolated from the line voltage for system safety.

Temperature Limits: -40 to 140°F (-40 to 60°C).

Storage Temperature Limits: -40 to 176°F (-40 to 80°C).

On Time: 10 msec to 600 msec, 10 msec steps.

On Time Accuracy: ±10 msec.

Off Time: 1 second to 255 seconds, 1 second steps.

Off Time Accuracy: ±1% of the value or ±50 msec, whichever is greater.

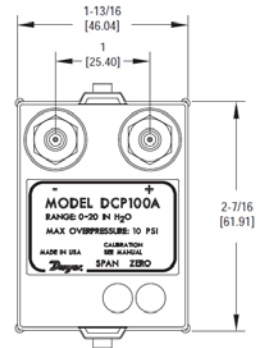
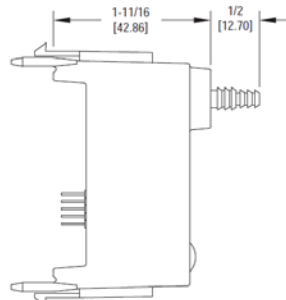
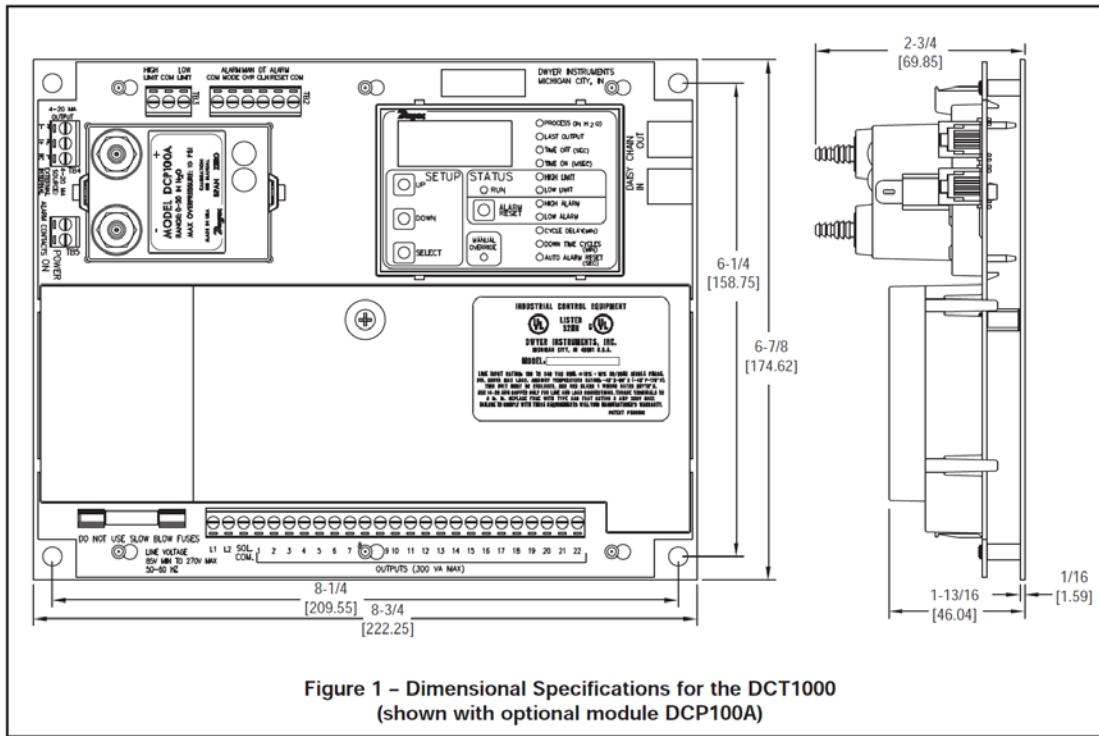
Weight: 1 lb 3.0 oz (538.6 g).

Agency Approvals: UL, cUL.

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Fax: 219/872-9057

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e-mail: info@dwyer-inst.com




The DCP100A or DCP200A pressure modules are designed exclusively for use with the Dwyer DCT1000 Dust Collector Timer Controller boards for on-demand cleaning requirements. These series of modules are available in 10' w.c. [2.49 kPa] or 20' w.c. [4.98 kPa] ranges, which allow for differential process pressure measurement as indicated on the display of the master controller. An isolated 4-20 mA readout channel is provided for remote pressure display. The 4-20 mA output may be wired either for use with an external power supply and indicator or using the isolated on-board 24 volt power supply to power the loop.

SPECIFICATIONS

- Pressure Ranges:** 10' w.c. or 20' w.c.
- Temperature Limits:** -40 to 140°F (-40 to 60°C).
- Pressure Limit:** 10 psi (68.95 kPa).
- Pressure Limit (differential):** 10 psi (68.95 kPa).
- Accuracy:** ±1.5% F.S. @ 73°F (22.8°C).
- Output Signal:** 4-20 mA.
- Alarm Contacts:** 1.5A inductive load, 3A resistive load @ 30 VAC or 40 VDC.
- Process Connections:** Two barbed connections for use with 1/8" (3.18 mm) or 3/16" (4.76 mm) I.D. tubing.
- Weight:** 5.5 oz (155.9 g).

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1.0 Installing the DCT1000

 **Warning:** Always install and service this device with the power off and a lockout installed if required. Line voltages will be exposed at the power/output connector and at the fuse. For this reason, we have installed a plastic guard to protect the user from accidentally contacting line voltages.

Please note that the power guard serves as a safety feature and should not be removed under any circumstances.

For ease of installation and maintenance, the connectors and fuse have been left unprotected. The open frame design of the DCT1000 will require an enclosure that meets appropriate safety and local code requirements. For optimal performance, the enclosure should also protect the controller from dirt, water and direct sunlight. There are no special orientation requirements, and the controller mounts easily using the mounting holes on the factory installed base plate.



Caution: Do not run control wires, communication cables, or other class 2 wiring in the same conduit as power leads. The system may malfunction if class 2 wiring is run together with power conductors.

1.1 Power Requirements

The controller has a "universal" power supply that will allow operation on 120 VAC to 240 VAC power lines. The input voltage must be between 85 VAC and 270VAC either 50 or 60 Hz. No circuit changes are required when switching between these voltages. The solenoid loads, however, must be sized to accommodate the line voltage selected.

1.2 DCT1000 Terminal Connections

The line and solenoid connections are located at the lower edge of the board below the plastic guard. The terminal block is a "Euro" style connector system that clamps the wire within the connector body. The connector will accept wire sizes from 14 to 22 AWG. The wire should be stripped to no more than 0.25 inches to avoid shorts or expose line voltages creating a potential safety hazard. To assist you in determining the proper wire gauge required, a strip gauge is provided at the lower right corner of the board. The connector system used on the DCT1000 is specified for single connection but you can piggyback to a single lug provided that local codes allow for this and good workmanship practices are followed. To power up the master controller and the channel expander, connect line power to L1 and L2 (see Dimensional Specifications, Figure 1). Connect the solenoids between the selected output and the solenoid common. Solenoid common and L2 are internally connected. Switches connected to the control inputs at the top of the board must be isolated contacts connected only to the relevant terminal and to the common terminals. The following subparagraphs describe the external switch connections. Refer to figure 2 for switch connection illustration.

1.2.1 External Pressure Connection

The controller may be used with an external pressure limit switch or sensor to provide demand-cleaning operation. The high limit and low limit inputs may be used for this purpose. A simple on-off system can be established with a single pressure switch connected to the high limit input. Better control can be achieved with a high and low limit switch/gage such as the Dwyer Photohelic®. In this on-demand mode, time on, time off, and cycle delay may be programmed to define the cleaning cycle. A three pin terminal block (TB3) provides connection for external high and low limit switches (see Figure 2 on the next page). These switches must be isolated contacts. The common line must not be connected to equipment ground or protective ground, since these may introduce electrical noise and cause improper operation or possible damage to the control board. The operation of these inputs are summarized as follows (see next page):

Current Operation	Low Limit Switch	High Limit Switch	Next Operation
Hold	Open	Open	Hold
Hold or Run	X	Closed	Run
Hold	∅	Open	Hold
Hold	Closed	∅	Run
Run	Closed	≠	Run
Hold	Closed	∅	Run
Run	≠	Open	Hold
∅ Transition from open to closed			
≠ Transition closed to open			
X Either open or closed			

Note: If a DCP100A or DCP200A pressure module is installed in the master controller, the switching functions are ignored.

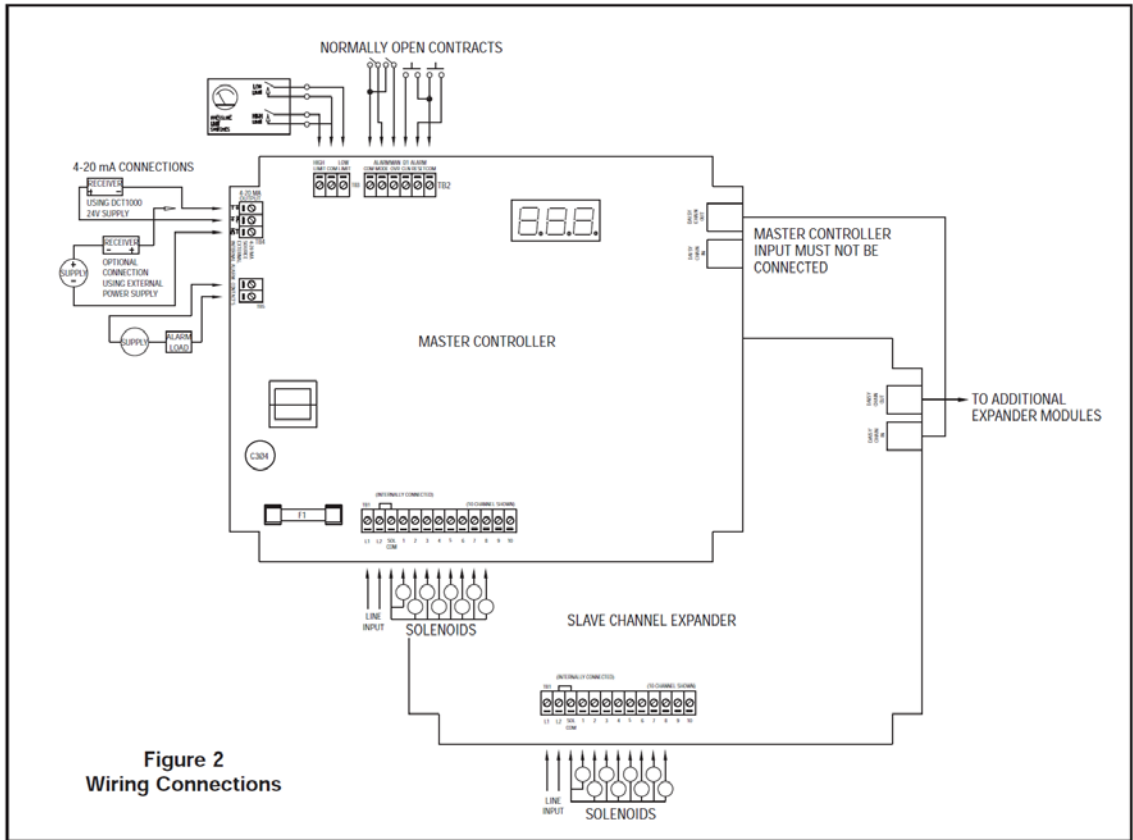


Figure 2
Wiring Connections

1.2.2 Manual Override Switch Connection

The manual override function allows the system to be set to the run mode regardless of other conditions. This mode is enabled when the manual override terminal and common are connected. It is disabled when they are disconnected. If the controller is to be run in continuous mode, a jumper wire may be wired across these terminals. When manual override is needed on a periodic basis, wire a SPST toggle switch between the manual override terminal and the common terminal.

1.2.3 Down Time Clean Connection

The down time clean operation forces the system into a run cycle for a programmed length of time between 0 – 255 minutes. The operation is initiated by connecting the down time clean terminal to a common terminal. This function is best accomplished through use of an external normally open switch.

1.2.4 Connecting Multiple Timer Boards

Both master controller boards and slave boards can have up to a maximum of 22 channels each. The system may be expanded up to 255 channels using master controller boards and slave boards. The DCT1000 will automatically detect the total number of channels involved and make their outputs available. You will note that both the master controllers and slave boards have a telephone style connector mounted on the upper right hand side of the board. These connectors are for use in systems requiring slave boards that must be daisy chained together to provide additional channel capability. For systems that require the slave boards, the master controller must not have any connection made to its daisy chain input unless it is designated as a slave control itself. (For larger systems requir-

ing more than three slave boards, a master controller must be used as the fourth slave board to satisfy power requirements.) This sequence would repeat itself until the limit of 255 channels has been reached. The cables used are not ordinary telephone style cables.



Caution: Do not use telephone jumper cables. These have a "twist" in the connection and may damage the controllers. Cables designed for use with the DCT1000 are available from Dwyer Instruments (Model DCAC02-2 ft., DCAC04-4 ft., etc.).

1.2.5 Continuous Cycle Mode

The master controller has several operating modes available for different applications. Starting with the most basic mode, it is capable of operating in a continuous cleaning cycle. This can be initiated by either placing a jumper between the high limit input and the common, or the manual override input to the common connection. Controlling this cycle are three setup parameters: time off, time on, and cycle delay. Time on and time off specifically deal with the solenoid on time and the time interval between the end of the on pulse and the start of the next. The cycle delay allows a delay of up to 255 minutes to be programmed between the end of one complete cleaning cycle and the beginning of the next. This allows additional options for defining a cleaning profile.

1.3 DCP Installation



Caution: Prior to installing the DCP100A/200A please review the operating specifications carefully. Some operating systems, especially in pneumatic conveying applications, may see static pressure or vacuum conditions that exceed the capability of the DCP100A/200A pressure module. For these conditions there are a number of alternate Dwyer pressure products that can be used to meet your application requirements, all of which can be terminated to the Dwyer DCT1000 Dust Collector Timer Controller. For more information on these and other Dwyer products, please call us at (219) 879-8000, or visit us on the web at www.dwyer-inst.com or www.dust-controls.com.

1.3.1 Location

The system should be located in an enclosure that meets relevant safety standards and electrical codes. There are no other special orientation requirements as the pressure module is not orientation sensitive. Care should be observed when routing the air hoses to ensure that any potential condensation or moisture will not drain into the sensor. Where heavy condensation is present, a drip loop or an in-line filter should be installed to ensure long term operation.

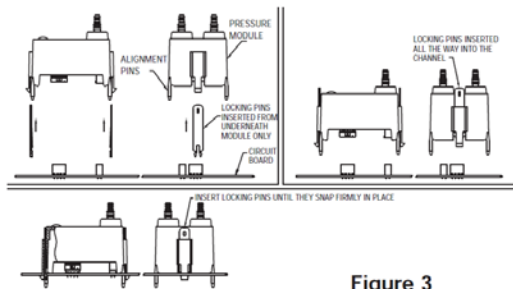


Figure 3
DCP Installation

1.3.2 Connecting DCP to Master Controller

The pressure module is attached to the Master Controller using integral connectors on both units. The insertion ports for the pressure module are located in the upper left quadrant of the DCT1000 Master Controller. The pressure module can be removed by compressing the retaining clips on each end of the module, then gently pulling the module out of the master controller board.

When inserting the module, the following procedure should be adhered to insure proper installation:

- Examine the bottom of the pressure module and note the orientation of the connectors.
- Align the module so that these connectors match the connector receptacles on the controller board.
- Orient the module with the four alignment pins over their respective mounting holes.
- Gently press the module into the connectors and snap the retaining clips on either end of the module into their slots.
- Always install and service this device with the power off and a lockout installed if required. "Hot" plugging the pressure module into an operating system may damage the system or cause the calibration parameters to be erased.

When installing or removing the module make sure to orient the module straight with board. Installing or removing the module at any angle may break the alignment pins.

1.3.3 Pressure Model Locking Pins

The DCP100A and DCP200A are supplied with locking pins to secure the module. In normal operation these are not required since the latching tabs are sufficient to secure the module even in a high vibration environment. However if the unit is to be shipped or used where severe mechanical shock could be encountered the locking pins ensure the module will not snap out of the board.

To install the locking pins, from underneath the module insert one pin behind each of the two latching tabs. Press these all the way into the channel. The ends of the tabs will extend through the slots at the top of these channels. Next insert the module in the board as described above, making sure it is properly aligned and snaps firmly in place. Press the exposed locking tabs down until the tab is seated behind the latch in the board. To remove the module, slide the locking tabs up using a small screw driver then remove the module as described above. See Figure 3.

1.3.4 DCP Connections

When a pressure module is installed, the 4-20 mA process signal and the alarm relay contacts are available. The 4-20 mA circuit is isolated from ground and other signals. The alarm relay contacts are isolated, normally open contacts. Pressure connections may be made to the stepped hose barbs with either 1/8" or 3/16" I.D. tubing.



Caution: Do not force the module into the connectors. Forcing the insertion may damage the connectors. Properly aligned, the module should snap into place.

1.3.5 DCP Maintenance

The pressure module should require very little maintenance under normal operational conditions. However, periodic calibration may be desirable to assure accuracy of the readings. The module may be removed and returned to the factory for calibration.

1.4 Alarm Mode Switch Connection

The auto alarm reset is controlled by the alarm mode switch connection. To enable the auto alarm reset the alarm mode input must be connected to a common connection. A jumper may be used when auto alarm reset is always active. A switch may be used if there are times that the auto alarm reset must be disabled. The switch must be an isolated contact and wired such that no connection is made between either of the wires and ground. See Figure 2 Wiring Connections.

1.4.1 Alarm Reset Switch Connection

The alarm may be reset either by pressing the Alarm Reset button on the control panel or by an external switch connected between the alarm-reset terminal and one of the common terminals. The alarm reset will only operate if the pressure module is installed and the pressure has returned to a normal condition. See Figure 2 Wiring Connections.

1.4.2 Connecting the 4-20 mA Loop

The pressure module provides an isolated 4-20 mA output, which may be used to remotely monitor the differential pressure across the dust bags or cartridges. The connection is made on the master control module at the terminal block designated for this signal. The connection is a 2-wire configuration with the option of using either an external 15 to 35 VDC power source or using the internal 24 VDC source. See Figure 2 Wiring Connections.

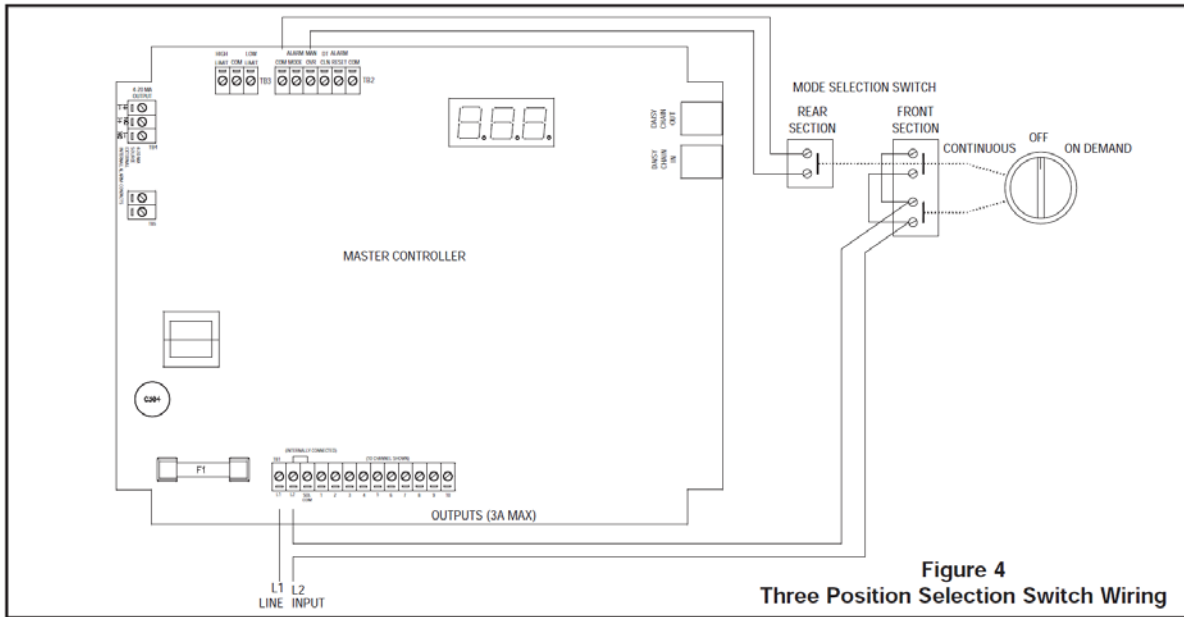


Figure 4
Three Position Selection Switch Wiring

1.4.3 Connecting the Alarm Relay

With the pressure module installed, a relay contact is provided for controlling an external alarm. This relay is a single form-A contact. It is activated when either the high alarm threshold is exceeded, or the pressure drops below the low alarm threshold. The connection is made at the two-pin connector TB5. See Figure 2 Wiring Connections

1.5 Three Position Selection Switch Wiring

An optional mode selection switch is available with the weather-proof enclosure. With this switch the user may select either continuous cleaning, on-demand cleaning, or off. This switch is supplied factory wired as shown in Figure 4. The switch has a front and rear section. The front section, consisting of two independent contacts, controls the power to the board. These contacts must be wired in parallel as shown in the diagram. The rear section controls the manual override, which when closed will force the system into a continuous must be reconnected, follow the wiring diagram.

Caution: Do not interconnect the low voltage manual override leads with the power leads. This will destroy the control board as well as pose a serious shock hazard

2.0 Programming the DCT1000 Master Controller

We've made it easy to navigate the DCT1000. Menu items can be accessed simply by pressing the "SELECT" button. The menu item that you are currently accessing is indicated by the illumination of an LED. To change menu items, all you have to do is push "UP" to increase a value or push "DOWN" to decrease a value. There are no keystrokes that you need to memorize, special combinations, or passwords that are required.

The master controller is equipped with an on board display and programming information center. The controller will power-up with the process indicator illuminated. If a pressure module is installed, the display will indicate the measured pressure in inches of water (w.c.); otherwise it will normally be blank.

2.1 • Last Output

The Last Output setup selects the last channel to be activated. When first selected, the display will flash the last output available in the system. With single board installations, this will be the number of channels installed, typically 6, 10 or 22. This value becomes more important when multiple modules are installed. The last output value flashed will be the sum of all channels available in the system.

After the last available channel indication has completed, the currently programmed last channel value is displayed. This value may be changed using the "UP" and "DOWN" buttons. The minimum value is one while the maximum value is the maximum number of installed channels, including all expansion modules.

The default value is the maximum number of channels. Pressing "SELECT" will change the setup mode to Time Off Setup.

2.2 • Time Off (Sec.)

Time off defines the period of time between solenoid activations when no channels are enabled. This may be set between one second and 255 seconds. The factory default is 10 seconds. The display will show the current time off setting when the time off setup mode is entered. The value may be changed using the Up and Down buttons. Pressing both "UP" and "DOWN" simultaneously and holding for approximately four seconds will restore the default value of 10.

2.3 • Time On (msec)

Time On Setup sets the solenoid on time. The display will indicate the currently programmed time on setting. This is measured in milliseconds. Using the "UP" and "DOWN" buttons, the value may be changed. The value may be set between 10 msec and 600 msec in 10 msec increments. Pressing the "UP" and "DOWN" buttons simultaneously for approximately four seconds will restore the factory default value of 100 msec. Pressing the "SELECT" button will advance the setup mode to the High Limit setup if the pressure module is installed. With no pressure module, it will step to Cycle Delay Setup.

2.4 • High Limit [Only available when DCP connected]

The High Limit Setup, available only with a pressure module installed, sets the pressure at which the cleaning cycle will begin. This value may be between zero and the pressure module full scale pressure. Normally, the High Limit should be above the Low Limit. If, however, the High Limit pressure is set below the Low Limit, the cleaning cycle will begin when the High Limit is exceeded and stop when the pressure falls below the High Limit. The Low Limit in this case will have no effect. Pressing "SELECT" will change the system to the Low Limit Setup mode.

2.5 • Low Limit [Only available when DCP installed]

The operation of the Low Limit, available only with a pressure module installed, is identical to the High Limit except this value sets the pressure where the cleaning cycle will end. The upper settable value is the calibration pressure of the pressure module and the lower limit is zero. Pressing "SELECT" will change the system to the High Alarm Setup mode.

2.6 • High Alarm [Only available when DCP installed]

The operation of the High Alarm Setup is identical to the High and Low Limit Setup and is only available when a pressure module is installed. The High Alarm default is 0. The upper settable value is the full scale pressure of the pressure module and the lower limit is zero. Pressing "SELECT" will change the system to the Low Alarm Setup mode.

2.7 • Low Alarm [Only available when DCP installed]

The operation of the Low Alarm Setup is identical to the High and Low Limit Setup. The Low Alarm default is 0. The upper settable value is the full scale pressure of the pressure module and the lower limit is zero. Pressing "SELECT" will change the system to the Cycle Delay Setup mode.

2.8 • Cycle Delay (min)

The cycle delay inserts a delay time between the end of the last channel and the beginning of the first channel. This may be set to between zero and 255 minutes. The factory default is zero. Setting the value to zero will disable the delay. Pressing "SELECT" will change the system to the Down Time Cycles Setup mode.

2.9 • Down Time Cycles (min)

The Down Time Cycles setup will select a value between zero and 255 minutes. The factory default is one minute. Selecting zero will disable the operation. When the down time cycles is activated by shorting the down time cycles input to the common terminal, (see figure 2) the system will enter a forced cleaning mode for the programmed duration. *NOTE:* The cycle delay, if one is programmed, will not be inserted in the timing cycle. Pressing "SELECT" will change the system to the Auto Alarm Reset Setup mode, if a pressure module is installed, or to Process when no pressure module is available.

2.10 • Auto Alarm Reset (sec) [Only available when DCP installed]

The Auto Alarm Reset Setup, available only when a pressure module is installed, allows the auto alarm reset time to be selected. This value may be set between zero and 255 seconds. The factory default value is five seconds. When the auto alarm reset is enabled by shorting the auto alarm reset terminal to a common terminal, (See Figure 1) the alarm will be reset after the pressure returns to the normal range and the timeout has expired. Pressing "SELECT" will change the system to Process mode.

3.0 Maintenance Support and Diagnostics

We have also included a number of features that will aid maintenance personnel in diagnosing problems or verifying that the system is operating.

3.1 Restoring Factory Defaults

The DCT1000 has been programmed with factory default values that meet most industry operating conditions. In the event that you want to restore all of the parameters to the original factory default values:

- (1) Return the master controller to the process mode.
- (2) Press and hold both "UP" and "DOWN" buttons.

The display will indicate a 10-second countdown, at the end of which all parameters will be restored to factory defaults. Releasing the switches prior to the end of the count will stop the process and no modification will be made. Likewise, in each of the parameter setup modes, pressing and holding the "UP" and "DOWN" buttons simultaneously will reset the individual default value, leaving other settings unchanged.

3.2 Power Indicator

A power on LED indicator is provided at the center left edge of the board. This will be illuminated when the power supply is operating properly. If the power LED is not illuminated, the primary power may be off or there is a fault in the power circuit.

3.3 Active Channel Indicator

Located just above the solenoid terminations, you will find that each channel is provided with an LED that is illuminated when the triac switch is on. This allows a visual correlation between the channel being pulsed and the operation of the solenoid.

3.4 Comm Check Indicator

The comm check indicator can be found in the upper right hand corner of the slave and master controller board (just above the "out" terminal, a telephone style connector). This indicator is used for two purposes. First, on a master controller a brief flash once per second is produced to indicate that the system is operating. Second, this indicator is used to show when the communication check operation is performed on slave boards. The master controller will check each of the slave boards at a rate of about one inquiry per second, starting with the slave board connected directly to the master controller and ending with the last slave board in the chain. The master controller will flash its Comm Check LED for about 250 msec each time it makes a communication check. The external module selected for test will also flash its Comm Check LED for about the same time each time it is interrogated. Observing this test sequence will indicate that the communication between boards is operational. When a slave board powers up, the Comm Check LED will be illuminated continuously. It will be extinguished when the master controller has initialized its communication channel. This indicator then shows that a master controller is operating and that each slave board is responding properly on the daisy chain.

3.5 Error Codes

Error codes will be displayed on the three-digit display when certain faults occur. Most of these indicators are associated with the daisy chain communication, but certain error codes pertain to single board operation also. These codes are:

Display	Meaning	Action Required
Err 1	This is a "watchdog" reset that is enabled when the master controller isn't able to cycle through its operation.	Make sure all electrical connections are appropriately shielded so the master controller is not disrupted by noise.
Err 2	The pressure module has failed to respond to the request of the master controller.	The master controller will try to recover from the fault. If unsuccessful, replace the pressure module.
Err 3	Communication error in the daisy chain interface. This will only appear when the master controller is used in conjunction with a slave board.	Make sure the control cable used in the daisy chain interface is properly shielded from noise.
Err 4	The master controller has detected a change in module configuration or a fault in one of the modules.	Reinstall all modules in accordance with the instructions in the factory IOM.
Err 5	If the fault described in "Err 4" is not corrected, the master controller will reconfigure the modules that are responding properly and operate at a degraded condition.	Reinstall all modules. Contact factory if the problem persists.
Err 6	A message error affecting the software of the master controller or one of its modules.	Check the integrity of all connecting cables used to drive slave boards for additional solenoids. Also check the electrical grounding of the system installation.
Err 7	Indicates that one of the triac drivers are not functioning.	Return to factory for evaluation and repair.
Err 8	Internal Error.	Contact the factory.
Err 9	Unassigned message code.	Contact the factory.

4.0 Glossary of Terms

- **Run Mode:** The term used when the timer board is firing the solenoids.
- **Pressure Module:** The pressure measurement subsystem that includes the software and hardware for on-demand cleaning, alarms and signal retransmission of the process variable (i.e., the differential pressure across the dust bags).
- **Master Controller:** The primary timer board that contains all of the major features, connections for external inputs and power to drive the DCT1000 Dust Collector Timer Controller system.
- **Power Guard:** A plastic shield that covers the output triacs and other line voltage circuitry.
- **Demand Cycle Mode:** A process in which the run mode is enabled through the on-board pressure module or an external switch such as the Dwyer Photohelic®.
- **Euro Connector:** A "caged" connection used to terminate solenoids, incoming power, or external switches on the DCT1000.
- **Continuous Cycle Mode:** A time based cycling mode dependent on solenoid time on/off settings and time set between complete cycles.
- **Manual Override:** Allows the user to override the DCT1000 remotely or from the master controller panel through use of a switch or a wire jumper.
- **Slave Board:** A channel expander that is used in conjunction with the master controller to accommodate additional solenoids on larger dust collection systems. It can be recognized easily as it does not have the on-board display panel or the power supply present. A master controller may also be used as a slave board.

Still need help? Please feel free to contact one of our customer service representatives at 219-879-8000 or visit us on the web at www.dwyer-inst.com or www.dust-controls.com. Thank you for choosing Dwyer Instruments.